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Title: Development of an Automated Training Device for Macaque Monkeys

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Abstract

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Macaques are often utilized in scientific research because of their genetic and physiological similarities to humans. Training macaques is difficult due to their smart minds, differences between individuals, and complicated social groups. Moreover, conducting research on complex tasks requires extended and time-consuming training periods. To address the challenges of training monkeys, we aimed to create a device to mitigate these difficulties and reduce training duration. We created a cost-effective device using basic equipment such as a touch screen monitor and a personal computer. This portable, remote-controllable device is open-source. It allows for code modifications, and is adaptable for use with other primate species. The Automated Training Device (ATD) was designed to allow animals to participate in training and tasks within their home cage without time constraints. A notable feature of this automated device is its ability to adapt to the individual preferences and abilities of macaques. By offering a range of engaging activities, this device helps primates develop a sense of independence and control over their environment, encouraging self-teaching. In this study, we describe how we created a device to teach primates. We explain the steps involved in training them, starting with basic tasks such as touching the screen and advancing to more complex ones like Delayed Match-to-Sample (DMS) task. It took 30 days for monkey M1 and 33 days for monkey M2 to complete the training, progressing from touching the monitor to learning the DMS. This period is significantly shorter than traditional monkey training outside the cage, making this method a promising alternative.

Introduction

Macaques are often chosen for scientific research due to their genetic and physiological similarities to humans, providing valuable insights into biology, medicine, and behavior. Given their high intelligence and complex cognitive abilities, training these animals requires careful consideration of their behavioral, social, and cognitive traits (1). Recognizing the challenges and time constraints, we opted to conduct basic training for the macaque within its home cage. This decision aimed to streamline the training process and minimize the duration required for effective skill acquisition.

In typical scenarios, non-human primates (NHPs) are often taken temporarily out of their home cages to undergo training in specialized experimental settings. One crucial consideration in this training process is the time devoted to it. To achieve this, experimenters transfer the animal from its home cage to a chair in the laboratory. McMillan et al. (2017) (2) found that the average time required to prepare monkeys for chair restraint varied, usually ranging from 2 to 8 weeks. These differences indicate variations in training approaches, considering factors such as the individual monkey's temperament (3-5) and the use of techniques like pole and collar methods (6, 7). Additionally, some studies have shown that the training period for complex cognitive neuroscience projects can often extend over several months. However, in-chair training in the laboratory is a time-intensive process with inherent limitations. Initially, training inexperienced monkeys can be demanding, occurring outside their familiar environment and within a constrained time frame. NHPs, with their diverse temperaments, may exhibit pathological and self-injurious behaviors in response to experimental demands (8, 9). Teaching monkeys' complex tasks, such as paying attention and temporarily remembering information, is a lengthy process. These tasks require intricate cognitive abilities, such as sustained attention and working memory. Due to these factors, a significant amount of time is necessary to ensure that monkeys learn and effectively display these cognitive skills. To expedite this process, we can create a device that enables all stages of monkey training within their living environment or a simulated game setting. Several previous experiments have opted for training animals within their home cages rather than using in-chair training in the laboratory (10–15). Many of these groups have used a computerbased interactive environment interface for individual or group housing of animals (10–15).

Additionally, in-cage training systems allow researchers to initiate task training even before animals are accustomed to being transported to the laboratory (8). Each system focuses on specific aspects, each with its own limitations. None of these systems encompass all the features, including portability, cost-effective construction, remote control, open-source code, compatibility with different cage types, and real-time observation of monkey behavior during tasks.

We developed a wireless, self-contained touch screen-based training system (Figure 1). It allows remote monitoring and task adjustments while the subject is engaged. The system is cost-effective, lightweight, portable, and sturdy, designed for monitoring subjects without requiring a constant lab presence. It allows task learning and modification without moving rhesus NHPs from their living environment and is adaptable to different cage types. This setup allows rhesus NHPs to engage in tasks at their convenience. Additionally, the system's open-source code enables teaching various behavioral tasks to NHPs. Named An Automated Training device (ATD) for Macaque Monkeys, this system is easily implementable and modifiable, even for researchers with basic hardware and software knowledge.

Our system is designed to teach NHPs motor tasks using a touchscreen right in their home cages. This innovation represents a significant advancement in mammal education. We demonstrate the practical application of ATD by training rhesus macaques in a touchscreen-based delayed matchto-sample (DMS) task.

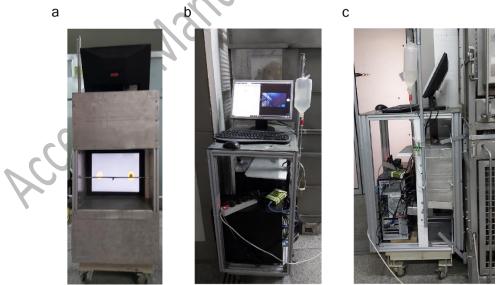


Figure 1. Automated training device (ATD). *a*, Front view of the device. *b*, Back view of the device. *c*, View attached to the cage of the device. ATD was attached to the home cage using two iron straps.

Method

Subject:

Two healthy adult male rhesus macaques (Macaca mulatta), aged 11 and 13 years, with a weight range of 10–13.5 kg, were subjects in the study. They had ad-libitum access to food and water. All experimental and behavioural procedures, including ATD use, were approved by the Institute's Fundamental Science Committee. The system was designed exclusively for in-cage macaque training. This portable system can be mounted on NHP cages, enabling in-cage training for all NHPs. Incorrecte

System Design

The system consists of three main parts:

- 1) Computer Setup:
 - a. Personal Computer
 - b. Touch Screen for Monkey Behavior
- 2) Reward System:
 - c) Peristaltic Pump DC 6V/12V
 - d) DC Motor L298N
 - e) Arduino Uno
 - f) Reward Source
- 3) Remote Control Unit:
 - g. Camera
 - h. USB Wi-Fi Adapter
 - The Fast Remote Desktop Application i.

Computer Setup:

To run software like MATLAB, the personal computer must meet specific minimum specifications, including an INTEL Pentium or Core i3 Processor, 2 GB of DDR3 RAM, and 2 VGA ports for display. The touch screen, serving as a secondary monitor, is linked to the computer via an HDMI cable. The monkey earns a reward by touching and choosing the correct stimulus or condition on the screen.

Reward System:

The reward system consists of a DC Motor L298N, an Arduino Uno, and a peristaltic pump (Figure 2). Arduino is an open-source hardware and processing platform for programming. The Arduino hardware is programmed using a wiring-based language within a processing-based environment, equipped with all necessary libraries. The Arduino Uno, based on the ATmega328 microcontroller, features 14 digital I/O pins, one USB port, and one power jack supporting 7 to 12 volts. The Arduino is programmed to use the computer's connected USB port to send the reward trigger signal and control the pump's activation and deactivation. To prevent interface disconnection and ensure rewards are given only for correct behaviour, the trigger must be sent within a maximum time of 3 seconds. The L298N module is a two-channel H-bridge driver for DC and stepper motors, with a maximum current of 2 amps per channel. A peristaltic pump, a positive displacement pump type, is employed for pumping various fluids, including fruit juice. After every successful attempt, a signal goes to the microcontroller. Then, the microcontroller turns on the pump for a set time, giving the monkey a reward. Accepted Manuscink



Figure 2. Schematic image of the reward system. The reward system comprises a 1). Personal computer (PC), 2). Arduino Uno, 3). DC motor L298N, 4). Peristaltic pump DC 6V/12V, 5). Reward output, 6). Reward source.

Reward system

Remote-Control Unit:

To enable remote control by our researchers, we connected the training system to the internet through a network card. Using desktop remote control applications like *AnyDesk*, researchers can access the training system from anywhere, enabling observation and control of the monkey through a connected camera. Remote tests or modifications are also possible, encompassing behaviors, reward reception during tasks, the quantity of rewards, and addressing any other issues.

Cage mounting frame

To effortlessly transport all the mentioned components, we required a frame equipped with wheel bases capable of accommodating and securing all these pieces of equipment. This frame serves as a mobile platform for easy movement and handling. The device comprises three key components: the computer system, reward system, and remote-control units, all strategically arranged on an aluminum frame. The specially designed cage mounting frame boasts dimensions of 50x60x90 cm, providing a sturdy and compact foundation shaped like a rectangular cube. Constructing this frame involved using four units of each of these sizes, totaling sixteen components. To enhance convenience in handling, the aluminum frame is thoughtfully equipped with four wheels, facilitating seamless portability. This design feature not only allows for effortless transportation but also ensures the device can be easily maneuvered and used in various locations, adding a practical and flexible dimension to its application.

Listed are the various parts of the in-cage training system and the minimum requirement for each part (Table 1).

Part Name	Minimum Requirement
Central processing unit (CPU)	INTEL Pentium or i3
RAM	2 GB DDR3
Graphics card	1 GB with 2 VGA port
Ports and interfaces	Includes 1 parallel port,2VGA port,1
	Serial port, and 1 RJ-45
Touchscreen monitor	ELO 1739L open-frame
Touchscreen LCD monitor	LAMSY
	Model: LR1703
	Display surface: Touch Screen for Finger & Stylus Input
~ <u>/</u> ()	Depth: 70 mm
	Display size: 17 Inch frame
<u> </u>	Resolution (SXGA): 1280 x 1024
	Touch controller port: USB
	Power: Input 210-240V, 1A, 50Hz
USB cable	USB 2.0 A to B cable
Pump	NE-4500 double OEM syringe pump
Camera	A4tech
	Model:pk:910p
	Rating:5v_230mA
	HD 720p to full HD 1080p
Cage mounting frame	50 x 60 x 90 cm
	Material: Aluminum
USB Wi-Fi adaptor	D-LINK N300

Table 1. Minimum requirements of the in-cage training system

Result and behavioral training

To assess the effectiveness and performance of the system, we initiated a training process involving two previously untrained monkeys. We successfully tested the system by training two macaques wirelessly and remotely within their home cages. This training approach avoided any need to remove the monkeys from their cages, eliminated physical contact between the animals and the experimenter, and eliminated the requirement for the monkeys to perform tasks within a designated time frame in a chair. With remote access, we could control the ATD from outside the animal's living environment. We began training the monkeys by having them touch the monitor, and gradually, we guided them through the step-by-step process of mastering the complex delayed match-to-sample task.

The system was activated at 12 p.m. and remained operational throughout the day during animal training, being switched off at 5 p.m. This setup provides the animals with unrestricted access to the system, allowing them to engage and rest at their convenience. The training sessions occurred five days a week, with two days designated as vacation days. To teach the DMS task, we employed a structured approach consisting of six steps. In each step, we closely monitored the animal's performance, ensuring a consistent correctness rate of over 85% for three consecutive days before advancing to the next step in the training process. The stimuli used in this study comprised 44 images divided into two main categories: faces and objects (Figure 3a). This systematic progression aimed to ensure a thorough and effective learning experience for the animal, establishing a solid foundation before introducing more complex elements of the task.

Step one: touching the monitor

In the initial step of our training process, our goal was to establish the association between touching the touch screen and receiving a reward. This fundamental connection was quickly acquired through repeated sessions within a single day (Every session included 200 trials, lasting approximately 15 to 25 minutes). To achieve this, we presented a sample image covering the entire touch screen, offering the animal a reward of fruit juice upon any touch to the screen. To make this interaction more attracting, we employed various methods known to be appealing to the animal, such as applying honey to the touch screen. This process continued until the animal successfully received juice, as illustrated in Figure 3b. Both Monkey M1 and M2 accomplished

step 1, involving screen touching, in 12 sessions across three days, with a mean performance of 100% in each session. During this stage, the monkeys did not make any wrong trials, resulting in a consistent performance of 100%. This foundational step laid the groundwork for subsequent training stages.

Step two: resizing the stimuli

In the second step, our objective was to facilitate the animal's acquisition of the association between image selection and reward reception. To achieve this, we systematically reduced the dimensions of the image continuously. The stimulus varied from one session to another, and if the animal successfully established a proficient association with the stimulus size, the subsequent session featured a smaller size. The gradual adjustment in size was implemented to facilitate effective learning by the monkey. Ultimately, we reduced the stimulus size from 1024x1280 pixels to a final size of 192x192 pixels (Figure 3c). Both Monkeys M1 and M2 successfully completed this step in 12 sessions over 3 days, maintaining an average performance of 100%. The overall mean performance across all days for both monkeys individually and their combined average performance was also 100%.

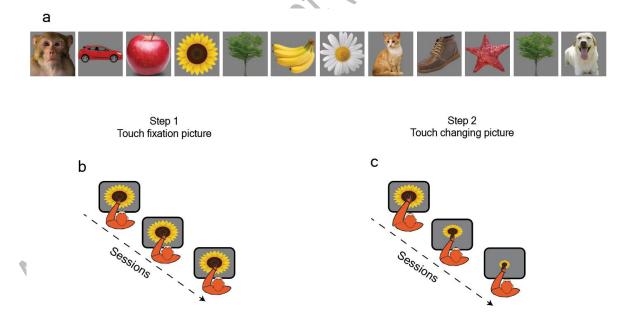


Figure 3. Delayed Match-to-Sample Task Training. *a*, Example visual stimuli used in the experiment. *b*, Step 1: Touch fixation picture. *c*, Step 2: Touch changing picture.

Step three: (random location of stimuli)

In the third step, our aim was to teach the animal to associate choosing images in various locations on the touch screen with receiving a reward. Additionally, we wanted to ensure that the animal focused on the sample image rather than just the center of the screen. From this stage onward, the size of the stimuli was set to 192×192 pixels. To fulfill the objective of the third step, we presented stimuli randomly in nine different locations on the screen. The monkey needed to accurately touch only the location of the displayed stimulus. If the monkey touched anywhere else on the screen, the trial was considered incorrect (Figure 4a). Monkeys M1 and M2 completed this step in 12 sessions over 3 days. Monkey M1 had a mean performance of $97\% \pm 2$ on day 1, $98.5\% \pm 1.4$ on day 2, and 100% on day 3. For Monkey M2, the mean performance on day 1 was $95\% \pm 1.6$, on day 2 was $96\% \pm 0.9$, and on day 3 was $97\% \pm 1.5$. Overall, the mean performance for all days reached $98.5\% \pm 0.87$ for Monkey M1, $96\% \pm 0.5$ for Monkey M2, and the combined average performance for both monkeys was $97.25\% \pm 0.7$ (Figure 4b).

After familiarizing the animal with the device in earlier steps, our focus shifted to teaching the delayed match-to-sample task (DMS). DMS task is a cognitive test used in psychology and neuroscience to assess working memory in animals, particularly primates. The task begins with the presentation of a sample stimulus (e.g., an image or object) to the subject. The subject is required to observe and remember this stimulus. After the sample presentation, there is a delay period during which no stimuli are presented. The length of this delay can vary, and it tests the subject's ability to retain information over a short-term memory interval. Following the delay, the subject is presented with a set of stimuli, which includes the original sample (matching stimulus) and distractors (non-matching stimulus). The subject's task is to select the stimulus that matches the one presented during the sample phase. A correct response occurs when the subject chooses the stimulus that matches the one from the sample phase. This indicates successful working memory retrieval.

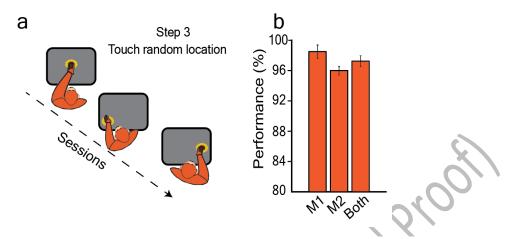


Figure 4. Delayed match-to-sample task training. a, step 3: touch random location. b, Mean performance in step 3. The calculation of the subject's performance involved dividing the number of correct trials by the sum of correct and wrong trials in each session, then multiplying by 100 [(correct trials / sum of correct and wrong trials) x 100]. Subsequently, we computed the daily performance of the subject. Overall, the average of all subjects' daily performance was calculated and reported as the subject's performance for learning each step in Figure 4 b. Mean ± SEM

Step four: visually guided touch

In the fourth training step, our objective was to introduce and teach the DMS task. Initially, a sample image was displayed at the center of the screen, and the animal received a reward for touching the image (sample presentation). Subsequently, a blank screen was presented to the animal for 1000 milliseconds (delay period), after which the same image randomly appeared on either the right or left side of the screen (choice phase). If the animal successfully touched the image, it received a reward (correct response); otherwise, it moved on to the next trial (Figure 5a).

Initially, the reward amount for both the sample presentation and correct response phases was the same. However, over successive sessions, we gradually decreased the reward for the sample presentation phase. Ultimately, only the correct response phase retained a reward. Monkey M1 had a mean performance of $55\% \pm 1.63$ on day 1, $74\% \pm 1.72$ on day 2, $78\% \pm 1.63$ on day 3, $83.3\% \pm 1.41$ on day 4, $88.8\% \pm 1.98$ on day 5, $88.7\% \pm 2.94$ on day 6, and $95.7\% \pm 1.38$ on day 7. Monkey M2 had a mean performance of $39\% \pm 1.78$ on day 1, $45\% \pm 1.41$ on day 2, $61.5\% \pm 1.44$ on day 3, $70.9\% \pm 1.23$ on day 4, $78.5\% \pm 1.42$ on day 5, $83.1\% \pm 2.22$ on day 6, $86.02\% \pm 1.31$ on day 7, $88.17\% \pm 0.91$ on day 8, and $91\% \pm 0.88$ on day 9. Overall, Monkey M1 took 28 sessions over 7

days to achieve a performance level exceeding 85%, while for Monkey M2, the same training step required 36 sessions spread across 9 days (Figure 5b).

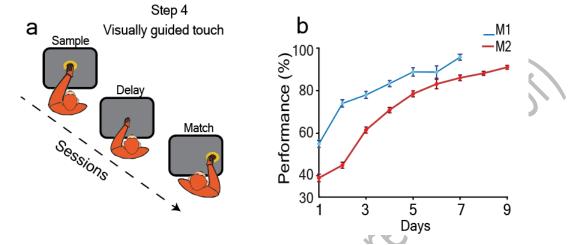


Figure 5. Delayed match-to-sample task training. a, step 4: visually guided touch. b, Mean performance in step 4. calculation of subject's performance in each session as mentioned in Figure 4. This step continued until the performance of the subject for 3 consecutive days is more than 85%. Mean ± SEM

Step five: teaching DMS task with transparency

In the fifth step, our goal was to train the association between receiving a reward and selecting a target image that matched the prototype image in the matching-to-sample phase, regardless of the distractor stimulus. Furthermore, we aimed to instill an understanding of the concept of the DMS task.

This step involved presenting a prototype image for the animal to touch. Afterward, there was a blank screen period of 1000 ms, followed by the appearance of two target pictures on the screen. One of these target images matched the prototype image, while the other served as a distractor image. The animal's objective was to select the target image that matched the prototype image to receive a reward. This step facilitated the animal's understanding of both the reward association and the basic concept of the DMS task (see Figure 6a). For a trial to be considered correct, the animal needed to choose the target image that matched the initial sample image. To enhance the animal's learning efficiency, we implemented a strategy by initially making the distracting image transparent. We initiated the image transparency at 0.6, and as the animal's performance exceeded 80%, we incrementally increased the transparency by 0.1. This approach aimed to optimize the learning process and facilitate a better understanding for the animal.

In the initial phase of this step, when images were introduced with a transparency setting of 0.6, Monkey M1 required 32 sessions spread over 8 days to achieve a performance level exceeding 80%. The mean performance of Monkey M1 for these 8 days with a transparency setting of 0.6 was as follows: $60.87\% \pm 1.85$ on day 1, $67.49\% \pm 1.51$ on day 2, $62.36\% \pm 1.86$ on day 3, 62.19%m \pm 3.23 on day 4, $63.25\% \pm 1.32$ on day 5, $74.91\% \pm 0.82$ on day 6, $77.3\% \pm 2.11$ on day 7, and $84.22\% \pm 2.45$ on day 8. Subsequently, we increased the transparency setting by 0.1 each day, and the average daily performance consistently stayed above 80%. On day 9, with a transparency setting of 0.7, Monkey M1 achieved a mean performance of $81.16\% \pm 0.67$, followed by $86.07\% \pm 3.21$ on day 10 for a transparency setting of 0.8, and $90.95\% \pm 2.14$ on day 11 for a transparency setting of 0.9.

For Monkey M2, it took 24 sessions across 7 days to surpass the 80% performance threshold at the initial transparency level of 0.6. The mean performance of Monkey M2 for these 7 days was as follows: $67.57\% \pm 1.13$ on day 1, $72.48\% \pm 1.85$ on day 2, $75.75\% \pm 1.51$ on day 3, $76.59\% \pm 1.86$ on day 4, $77\% \pm 3.23$ on day 5, $78.71\% \pm 1.31$ on day 6, and $80.75\% \pm 0.82$ on day 7. Then, in 8 sessions over two days, the performance reached above 80% for a transparency setting of 0.7, with mean performances of $78.02\% \pm 2.11$ on day 8 and $81.86\% \pm 2.45$ on day 9. Like Monkey M1, we continued to add 0.1 to transparency daily, and the average daily performance remained above 80%. Monkey M2 had a mean performance of $82\% \pm 0.67$ on day 10 for a transparency setting of 0.8, and $81.89\% \pm 3.21$ on day 11 for a transparency setting of 0.9. In summary, Monkey M1 and M2 completed this step in a total of 44 sessions over 11 days (see Figure 6c). This information highlights the individual learning trajectories of the monkeys during this specific training step.

Step six: DMS task

In this step, our aim was to master the DMS task. In the preceding step, the animal learned the DMS task with a transparent prototype image. In this current step, the testing procedure mirrored the previous steps, with a notable difference—the distractor image was no longer transparent (see Figure 6b). When the transparency of the images reached 1 (indicated by the dashed line on the plot, marking the initiation of the DMS task step), the DMS step commenced. Under this condition, Monkey M1 consistently demonstrated a mean performance above 85% for three

consecutive days, while Monkey M2 maintained this level for four consecutive days. On day 1, Monkey M1 exhibited a mean performance of $93.45\% \pm 1.11$, followed by $94.31\% \pm 0.57$ on day 2 and $92.76\% \pm 1.19$ on day 3. Monkey M2's mean performance on day 1 was $83.28\% \pm 2.14$, followed by $87.33\% \pm 1.11$ on day 2, $90.67\% \pm 1.01$ on day 3, and $90.29\% \pm 0.57$ on day 4. These consistent performances indicated that the monkeys successfully acquired proficiency in the DMS task (see Figure 6c). Overall, Monkey M1 learned the DMS task in 30 days, and Monkey M2 achieved proficiency in 33 days. This progression signifies the accomplishment of the learning objective in this step.

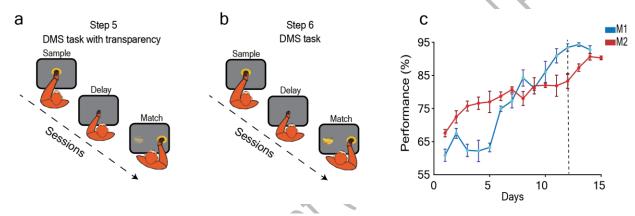


Figure6. Delayed match-to-sample task training. a, step 5: DMS task with transparency. b, Step 6: DMS task. c, Mean performance in step 5,6. calculation of subject's performance in each session as mentioned in Figure 4. This step continued until the performance of the subject for 3 consecutive days is more than 85%. The vertical dashed line indicates the start of step 6. Mean ± SEM.

Conclusion

We have developed a touch screen-based training system that's autonomous, wireless, costeffective, lightweight, portable, and robust. It is specifically designed for remote subject monitoring, eliminating the need for constant presence in the laboratory, and it can be adapted to various cage setups. This system is user-friendly and customizable by researchers with basic hardware and software knowledge. Our ATD outperforms previously published touch screenbased systems, offering a broader range of advantages. Touchscreen-based systems are often mentioned for being wireless (16, 17), affordable (16), light weight (16, 17), and portable (16–19, 13). However, to the best of our knowledge, there is no published system that fulfills all these criteria while also enabling remote subject monitoring and task modification.

Training systems within the animal's cage have the advantage of enabling researchers to start task training even before the animals are ready to be transported to the laboratory. McMillan et al.

(2017) (2) found that the average time needed to prepare monkeys for chair restraint varied, typically taking 2–8 weeks. These differences indicate variations in training approaches, considering factors such as the individual monkey's temperament (3–5) and the use of techniques like pole and collar methods (6, 7).Training NHPs before their introduction to research facilities has been noted to enhance their initial performance at the facility (20).

Our study revealed a significant reduction in the number of sessions required for task learning when conducted within the cage (21). In contrast, previous studies have suggested that monkeys generally take months and undergo numerous sessions to master the DMS task. Noteworthy, our findings show that Monkey M1 attained proficiency in the DMS task within a mere 30 days (120 sessions), while Monkey M2 achieved mastery in 33 days (132 sessions).

These systems lack an eye-tracking feature during training, depending solely on the monkeys' hand movements (17, 13, 22). Monkeys commonly use their eyes for tasks in the lab (23, 24). It's essential to grasp how monkeys learn through automatic touch screen devices, as it likely impacts their training time in the lab—a factor deserving more exploration. Our aim is to improve the automatic training system for cage-contained monkeys by adding an eye-tracking system. We expect this addition to substantially enhance monkey training within the cage.

On the other hand, environmental enrichment plays a crucial role in maintaining the welfare of nonhuman primates. However, monkeys may quickly lose interest in unchanging enrichment toys due to habituation(25). Sustaining the engagement of animals requires introducing variations and novelty in their surroundings, along with incorporating primary reinforcers like food or fluid rewards, diverse stimuli, or novel experiences (26). Several studies have proposed housing-based training as a valuable tool for the environmental enrichment of captive NHPs (27, 28). According to this proposal, cognitive training through an automated protocol that adapts the task difficulty based on the animal's current skill level could potentially enhance the animal's motivation for prolonged interaction with the device. Cognitive training through an automated protocol serves as a preventive measure against the onset of depression in animals and enhances the preservation of their mental well-being.

In our study, we demonstrated that two monkeys consistently used the device for several days, extending beyond a month, even when fluid and food intake were not restricted beyond training

sessions. This suggests that the ATD is a valuable tool for enhancing environmental enrichment (28, 27).

In summary, the development of an automatic training device for macaques represents a significant advancement in enhancing both the well-being of these intelligent animals and the field of scientific research. This innovative device empowers macaques to engage in tasks within ut unicks « .acilitates the te .or energy investment unicket u their cages, supporting their mental and physical health without external stressors. This breakthrough not only enhances ethical treatment but also unlocks exciting possibilities for scientific exploration. Furthermore, the device's efficiency facilitates the teaching of various tasks

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